

Human Safety Device using GSM and GPS Module

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Abstract— Security is the condition of being protected against danger or loss. In the general sense, security is a concept similar to safety. The nuance between the two is an added emphasis on being protected from dangers that originate from outside. Individuals or actions that encroach upon the condition of protection are responsible for the breach of security. The word "security" in general usage is synonymous with "safety," but as a technical term "security" means that something not only is secure but that it has been secured. This project is designed with ATmega328. This Project presents a women safety detection system using GPS and GSM modems. The system can be interconnected with the alarm system and alert the neighbors. This detection and messaging system is composed of a GPS receiver, Microcontroller and a GSM Modem. GPS Receiver gets the location information from satellites in the form of latitude and longitude.

Keywords— GSM Modem., ATmega328, GSM Modem. GPS Receiver

I. INTRODUCTION

The microprocessor-based system is built for controlling a function or range of functions and is not designed to be programmed by the end user in the same way a PC is defined as an embedded system. An embedded system is designed to perform one particular task albeit with different choices and options.

Embedded systems contain processing cores that are either microcontrollers or digital signal processors. Microcontrollers are generally known as "chip", which may itself be packaged with other microcontrollers in a hybrid system of Application Specific Integrated Circuit (ASIC). In general, input always comes from a detector or sensors in more specific word and meanwhile the output goes to the activator which may start or stop the operation of the machine or the operating system.

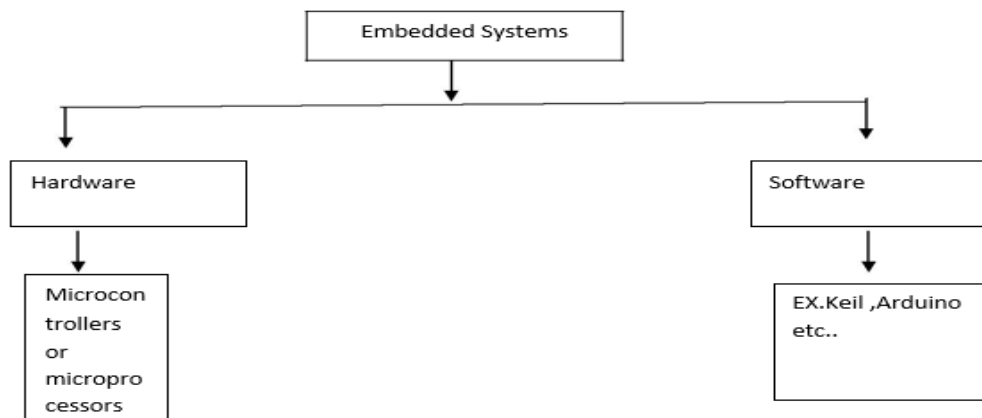


Fig. 1.1 Block Diagram of Embedded System

An embedded system is a combination of both hardware and software, each embedded system is unique and the hardware is highly specialized in the application domain. Hardware consists of processors, microcontroller, IR sensors etc. On the other hand, Software is just like a brain of the whole embedded system as this consists of the programming languages used which makes hardware work. As a result, embedded systems programming can be a widely varying experience. An embedded system is combination of computer hardware and software, either fixed incapability or programmable, that is specifically designed for particular kind of application device. Industrial machines, automobiles, medical equipment, vending machines and toys (as well as the more obvious cellular phone and PDA) are among the myriad possible hosts of an embedded system. Embedded systems that are programmable are provided with a programming interface, and embedded systems programming is specialized occupation.

II. GSM MODULE

Global system for mobile communication (GSM) is a globally accepted standard for digital cellular communication. GSM is the name of a standardization group established in 1982 to create a common European mobile telephone standard that would formulate specifications for a pan-European mobile cellular radio system operating at 900MHz. GSM (Global System for Mobile communications) is a cellular network, which means that mobile phones connect to it by searching for cells in the immediate vicinity. GSM networks operate in four different frequency ranges. Most GSM networks operate in the 900 MHz or 1800 MHz bands. Some countries in the Americas use the 850 MHz and 1900 MHz bands because the 900 and 1800 MHz frequency bands were already allocated.

The rarer 400 and 450 MHz frequency bands are assigned in some countries, where these frequencies were previously used for first-generation systems.

GSM-900 uses 890–915 MHz to send information from the mobile station to the base station (uplink) and 935–960 MHz for the other direction (downlink), providing 124 RF channels (channel numbers 1 to 124) spaced at 200 kHz. Duplex spacing of 45 MHz is used. In some countries the GSM-900 band has been extended to cover a larger frequency range. This 'extended GSM', E-GSM, uses 880–915 MHz (uplink) and 925–960 MHz (downlink), adding 50 channels (channel numbers 975 to 1023 and 0) to the original GSM-900 band. Time division multiplexing is used to allow eight full-rate or sixteen half-rate speech channels per radio frequency channel. There are eight radio timeslots (giving eight burst periods) grouped into what is called a TDMA frame. Half rate channels use alternate frames in the same timeslot. The channel data rate is 270.833 kbit/s, and the frame duration is 4.615ms.

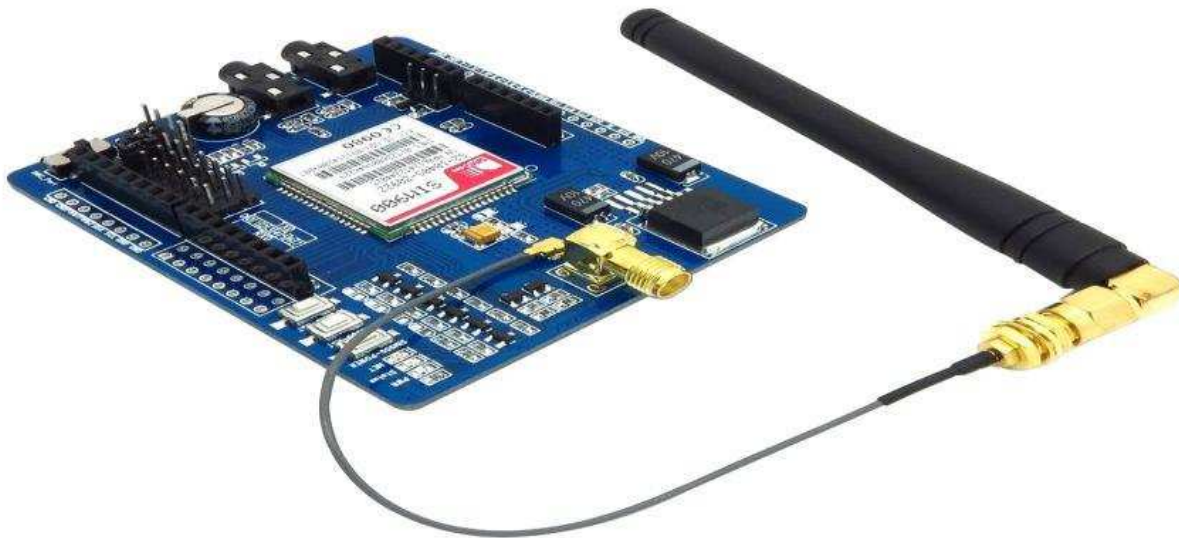


Fig.2.1 GSM module

A. Operation GSM

The basis of the GPS is a constellation of satellites that are continuously orbiting the earth. These satellites, which are equipped with atomic clocks, transmit radio signals that contain their exact location, time, and other information. The radio signals from the satellites, which are monitored and corrected by control stations, are picked up by the GPS receiver. A Global Positioning System receiver needs only three satellites to plot a rough, 2D position, which will not be very accurate.

III. HARDWARE IMPLEMENTATION

The Atmel AVR® core combines a rich instruction set with 32 general purpose working registers. All the 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in a single instruction executed in one clock cycle. The resulting architecture is more code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers. The ATmega328/P provides the following features: 32Kbytes of In-System Programmable Flash with Read-While-Write capabilities, 1Kbytes EEPROM, 2Kbytes SRAM, 23 general purpose I/O lines, 32 general purpose working registers, Real Time Counter (RTC), three flexible Timer/Counters with compare modes and PWM, 1 serial programmable USARTs , 1 byte-oriented 2-wire Serial Interface (I2C), a 6- channel 10-bit ADC (8 channels in TQFP and QFN/MLF packages) , a programmable Watchdog Timer with internal Oscillator, an SPI serial port, and six software selectable power saving modes.

This allows very fast start-up combined with low power consumption. In Extended Standby mode, both the main oscillator and the asynchronous timer continue to run. Atmel offers the Q Touch® library for embedding capacitive touch buttons, sliders and wheels functionality into AVR microcontrollers. The patented charge-transfer signal acquisition offers robust sensing and includes fully de-bounced reporting of touch keys and includes Adjacent Key Suppression® (AKS™) technology for unambiguous detection of key events. The easy-to-use Q Touch Suite tool chain allows you to explore, develop and debug your own touch applications. The device is manufactured using Atmel’s high density non-volatile memory technology. The On-chip ISP Flash allows the program memory to be reprogrammed In-System through an SPI serial interface, by a conventional nonvolatile memory programmer, or by an On-chip Boot program running on the AVR core.

The ATmega328/P is supported with a full suite of program and system development tools including: C Compilers, Macro Assemblers, Program Debugger/Simulators, In-Circuit Emulators, and Evaluation kits.

A. Flowchart

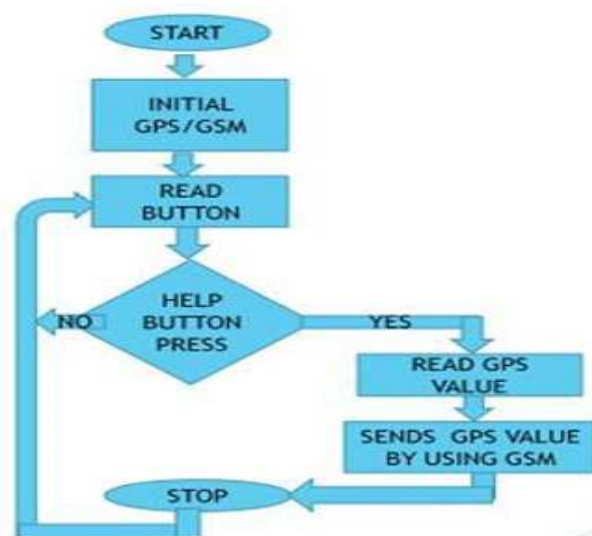


Fig. 3.1 Flow chart Working process

This project clearly uses two main modules of GSM and a microcontroller. The user when sends the messages through his phones those reaches the GSM ,through the AT commands all those messages reaches the microcontroller. That microcontroller takes the data in terms of bits through the Max232.Those information will be transmitted to the LCD display.

IV. RESULT & DISCUSSION

The aim of this project was to propose a cost effective voice controlled (Google Assistant) home automation controlling general appliances found in one's home. The approach discussed in the project was successful as GACHA's (Google Assistant Controlled Home Automation) design was successfully implemented. The implementation of project as shown in Fig. 4.1.

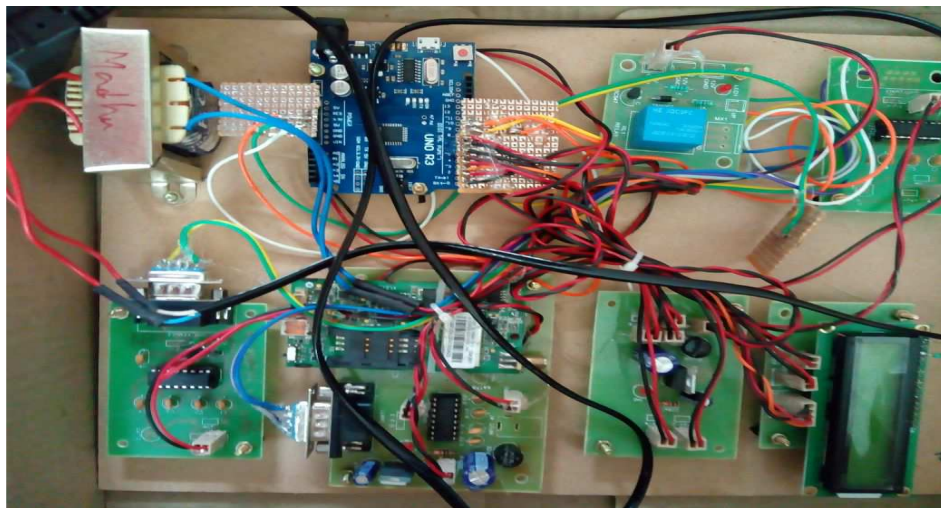


Fig. 4.1 Major Parts of Project



Fig. 4.2 Output in LCD



V. CONCLUSION AND FUTURE WORK

The aim of this project was to propose a cost effective voice controlled (Google Assistant) home automation controlling general appliances found in one's home. The approach discussed in the project was successful as GACHA's (Google Assistant Controlled Home Automation) design was successfully implemented. This system is highly reliable and efficient for the aged people and differently abled person on a wheel chair who cannot reach the switch for the switching ON/OFF the device and are dependent on others. The future scope for GACHA can be huge. There are many factors to improve on to make GACHA more powerful, intelligent, scalable, and to become better overall for home automation. For example, controlling the speed of the fan, more number of devices can be integrated, like a coffee machine, air conditioner etc. To make the system respond more faster own private Adafruit server can be made. Well, no system is ever perfect. It always has a scope for improvement. One just needs to put on a thinking cap and try and make the system better.

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